

A Standard Design Language for Autonomous Networks

Paul Harvey

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The Dream





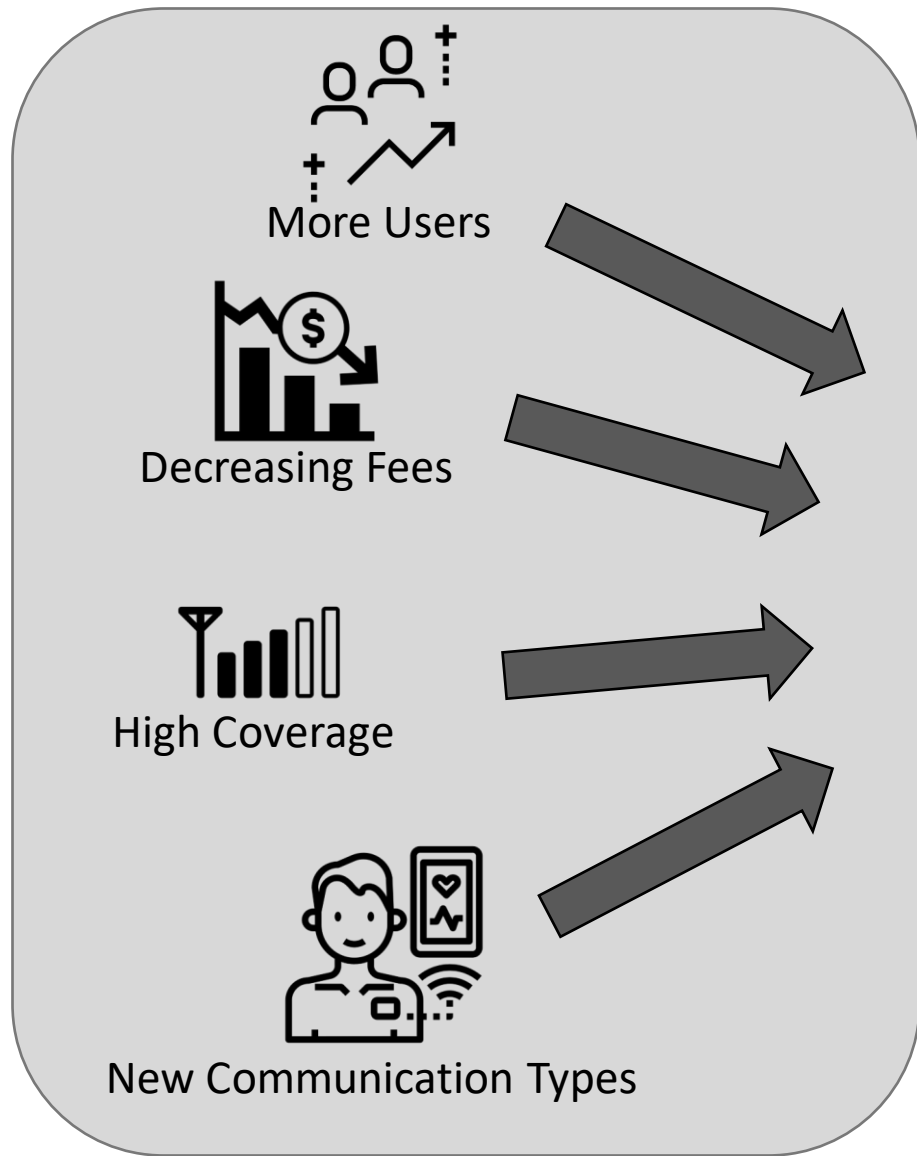




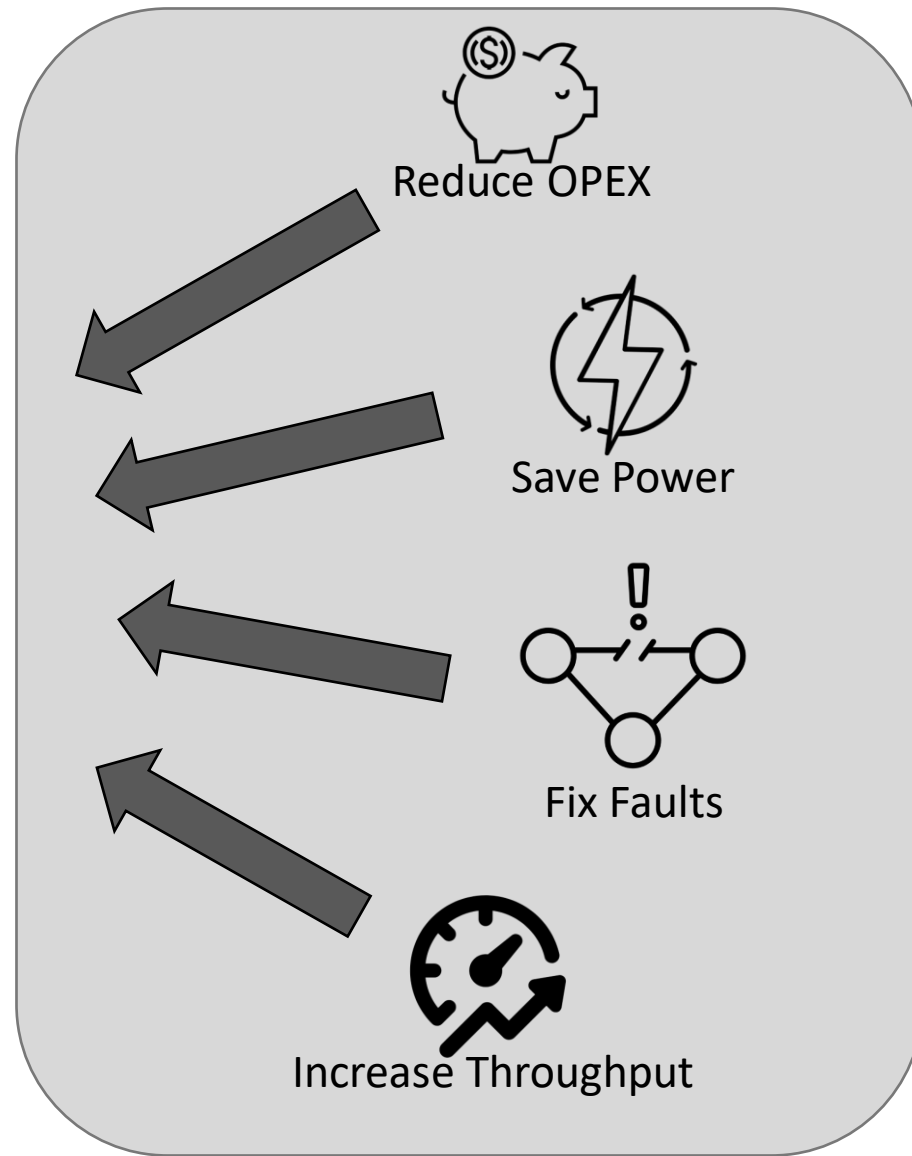


100 Years Later...

External Demand



Internal Demand



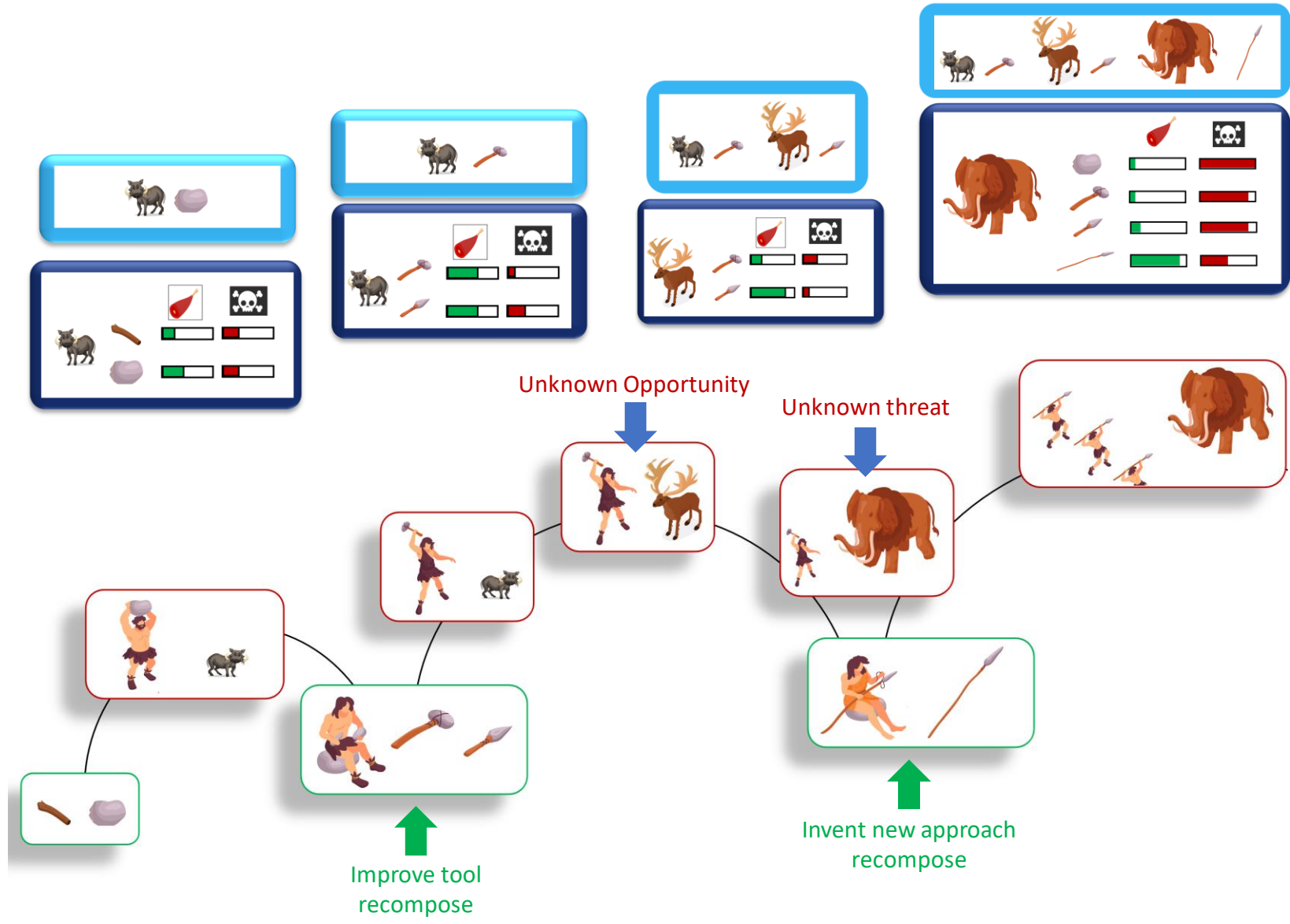
How to adapt to the unknown

Acquire Knowledge

Analyse Results

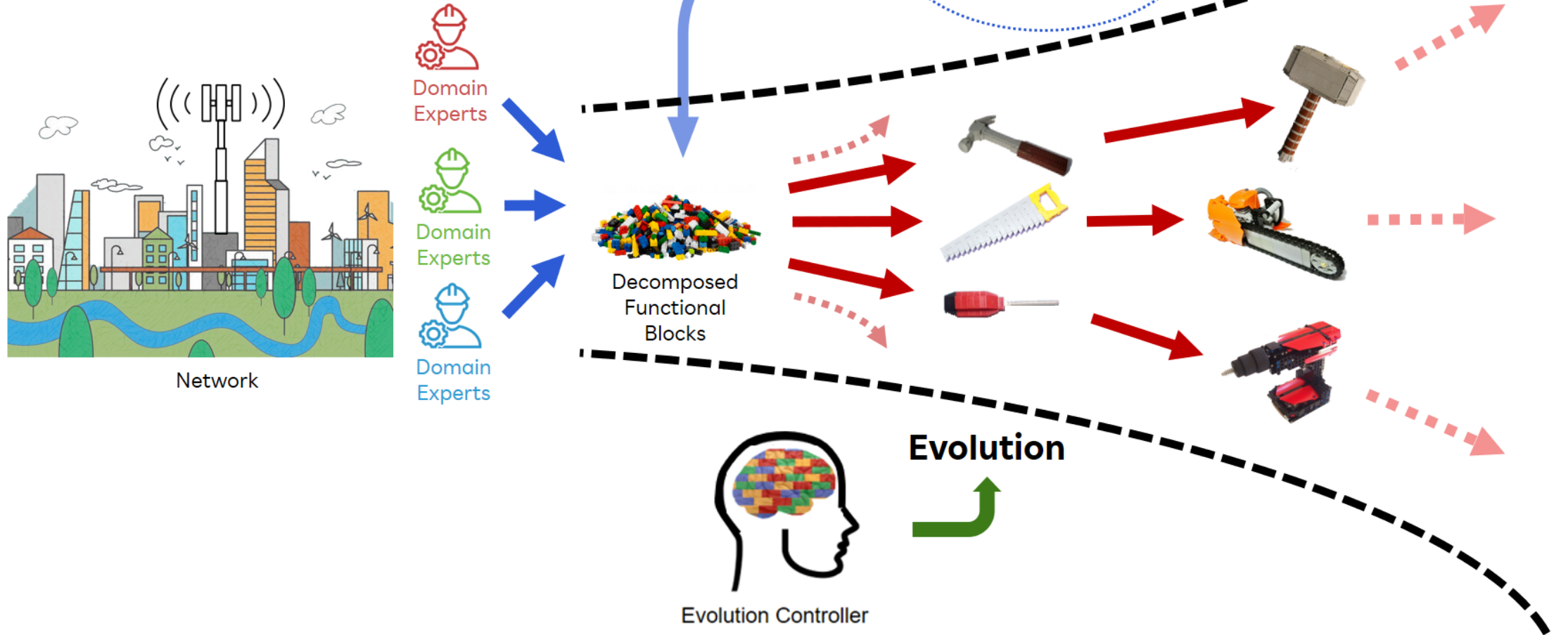
Experiment

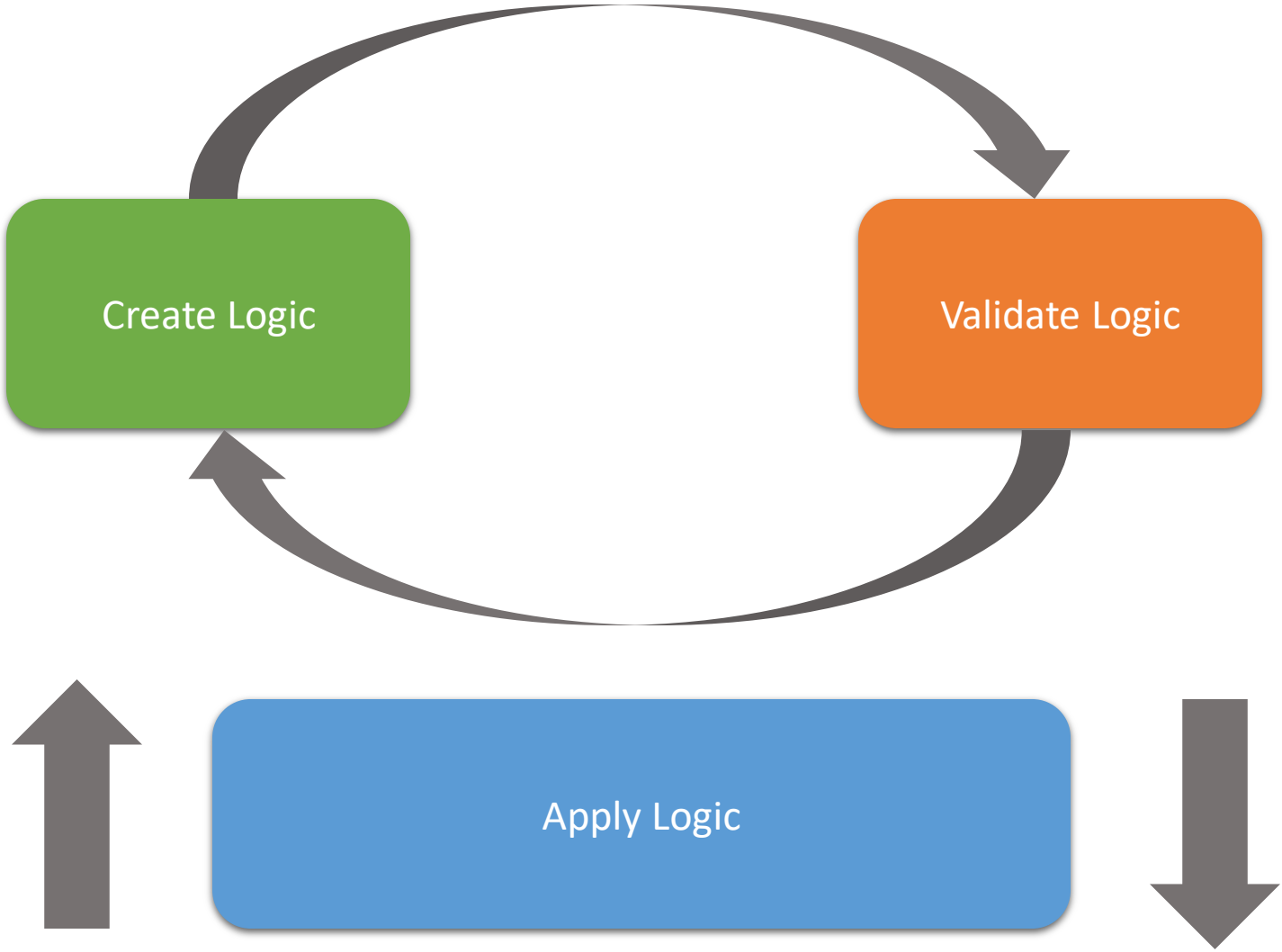
Discover Create



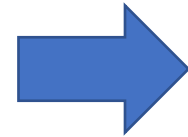
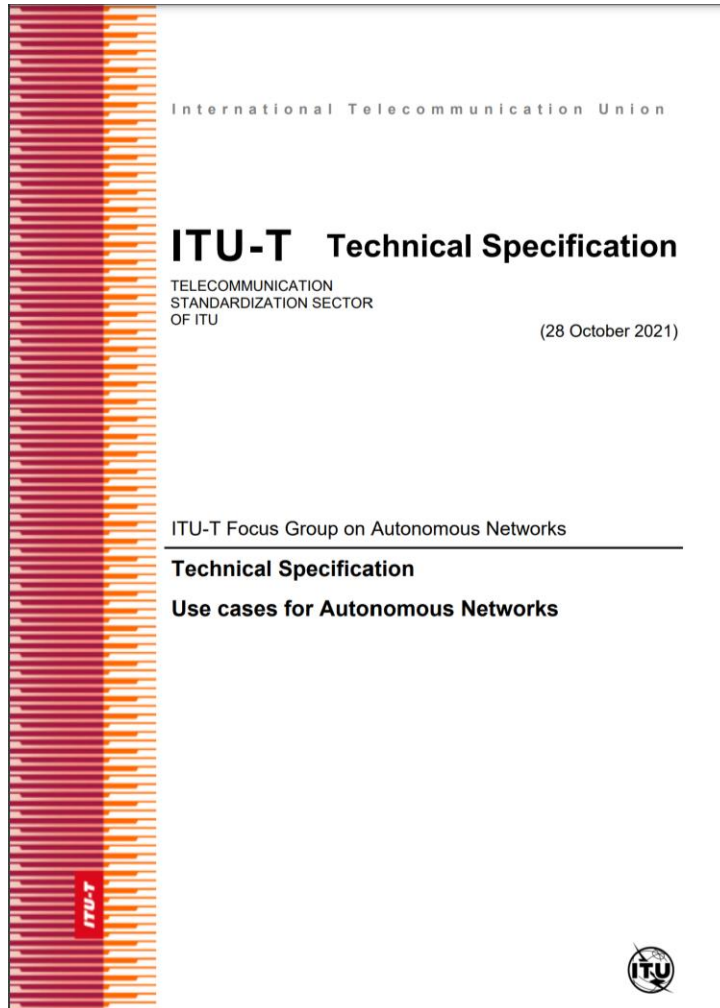
Evolutionary Autonomous Networks

Paul Harvey*, Alexandru Tatar, Pierre Imai, Leon Wong
and Laurent Bringuier

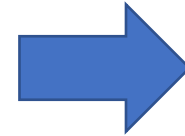




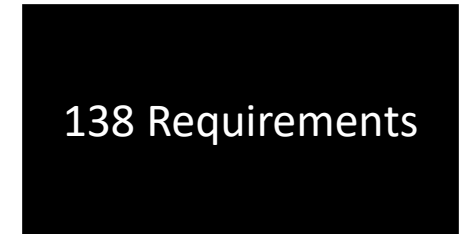
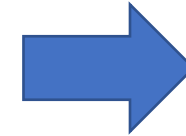
Process



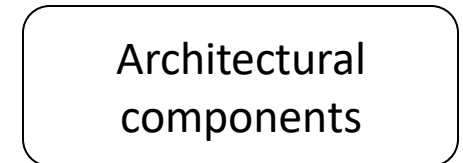
3 Key Concepts



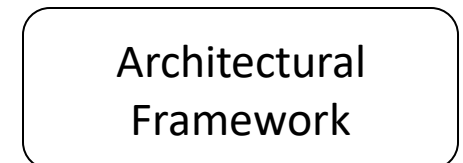
Architecture



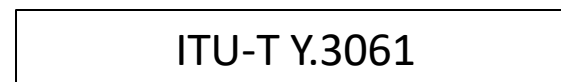
138 Requirements



Architectural
components



Architectural
Framework

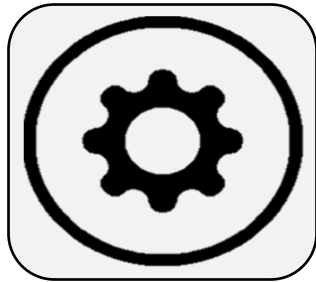


ITU-T Y.3061

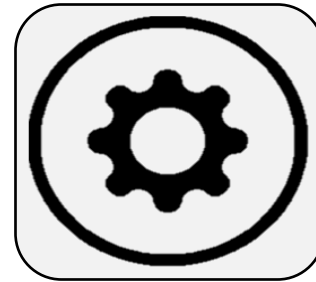
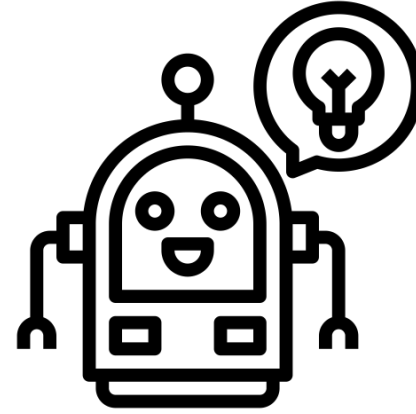


Requirements

- Requirements for Exploratory Evolution
- Requirements for Online Experimentation
- Requirements for Dynamic Adaptation
- Requirements for Knowledge
- Requirements for Autonomous Network Orchestration



Controller



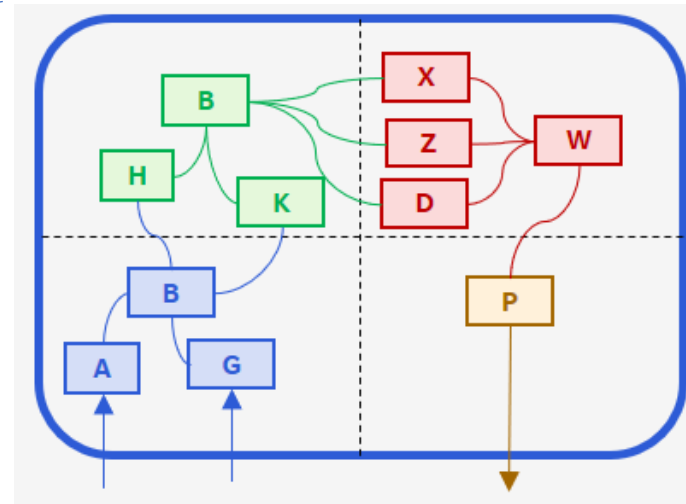
Controller

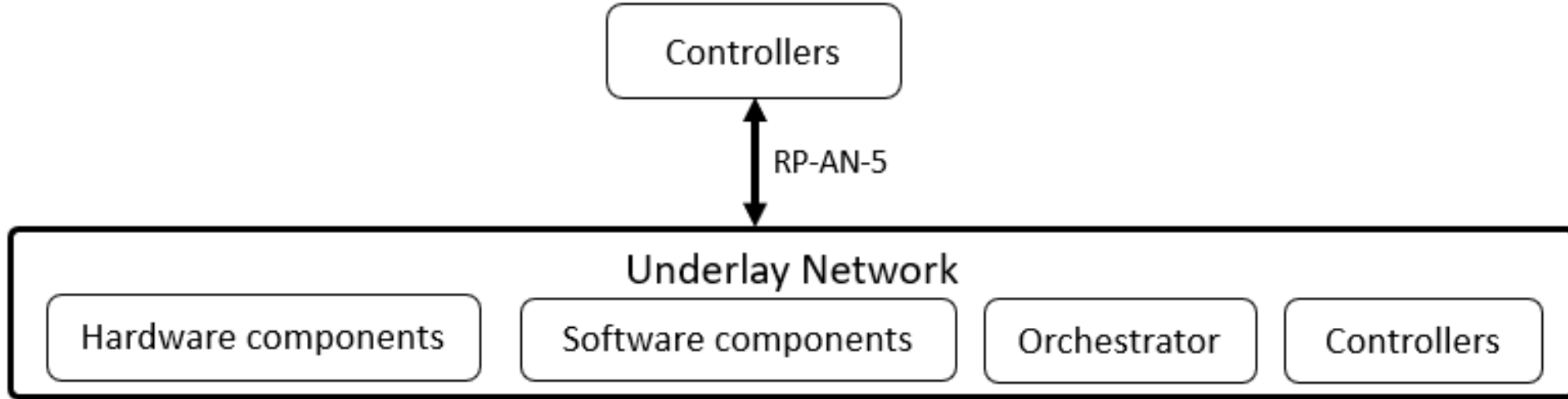
Definition 3.2.4: Controller

A workflow, open loop or closed loop of a system under control in an autonomous network, composed of modules, integrated in a specific sequence, using interfaces exposed by the modules, to solve a specific problem or satisfy a given requirement.



Controller





The interactions are:

- Controller interacting with hardware components.
- Controller interacting with software components.
- Controller interacting with an orchestrator or other software control mechanisms.
- Controller interacting with other controllers.

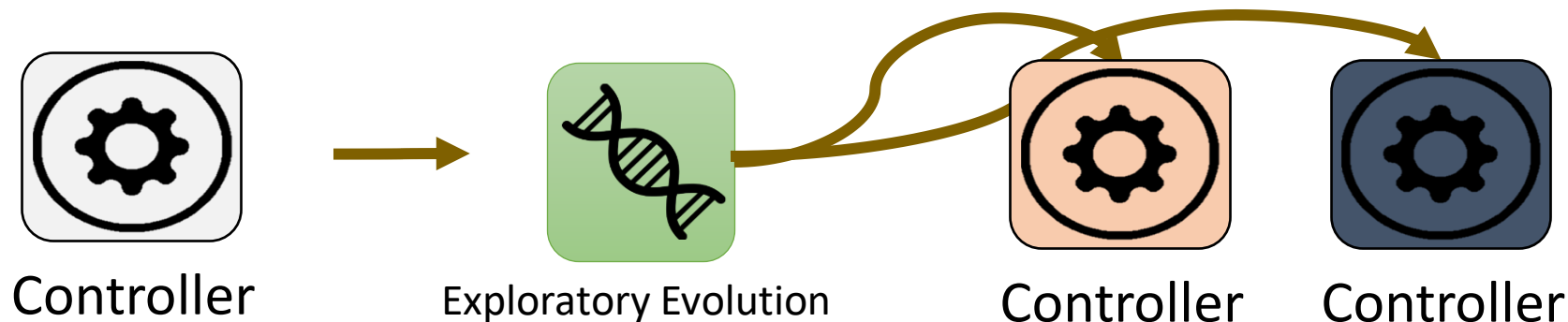
NOTE 4 - Building upon this simple representation, hierarchies of controllers may be formed.

Exploratory Evolution

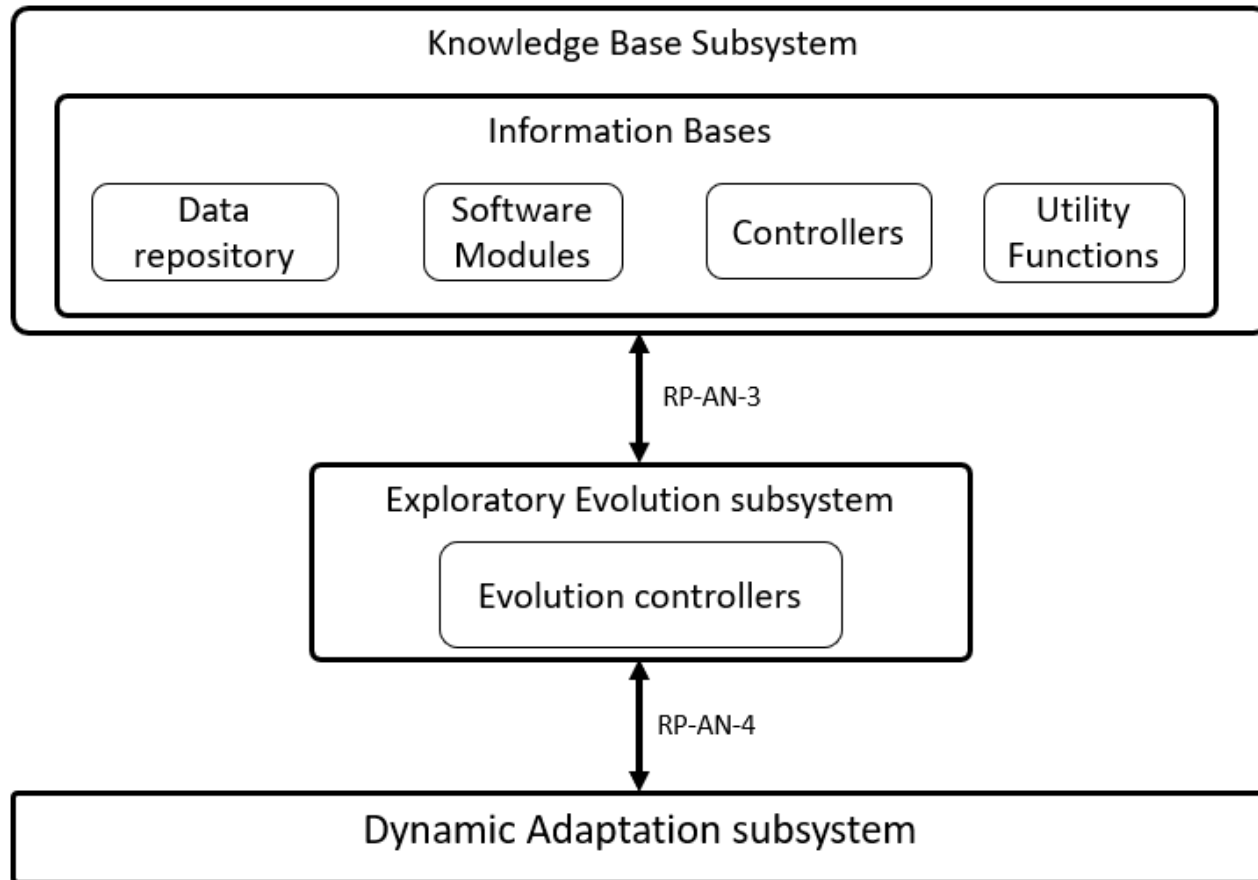
Exploratory evolution introduces the mechanisms and processes of exploration and evolution to adapt controllers in response to changes in the underlay network.

NOTE 1 - An example of a process that creates a controller is the composition of controllers from modules or other closed loops. This may involve the selection of modules which are used for composition.

NOTE 2 - An example of a process that modifies an existing controller is the dynamic change in the controller's structure by adding new modules, deleting existing modules, replacing existing modules, or rearranging the structure of a controller's modules, in accordance with the real time changes in the system under control.



Exploratory Evolution



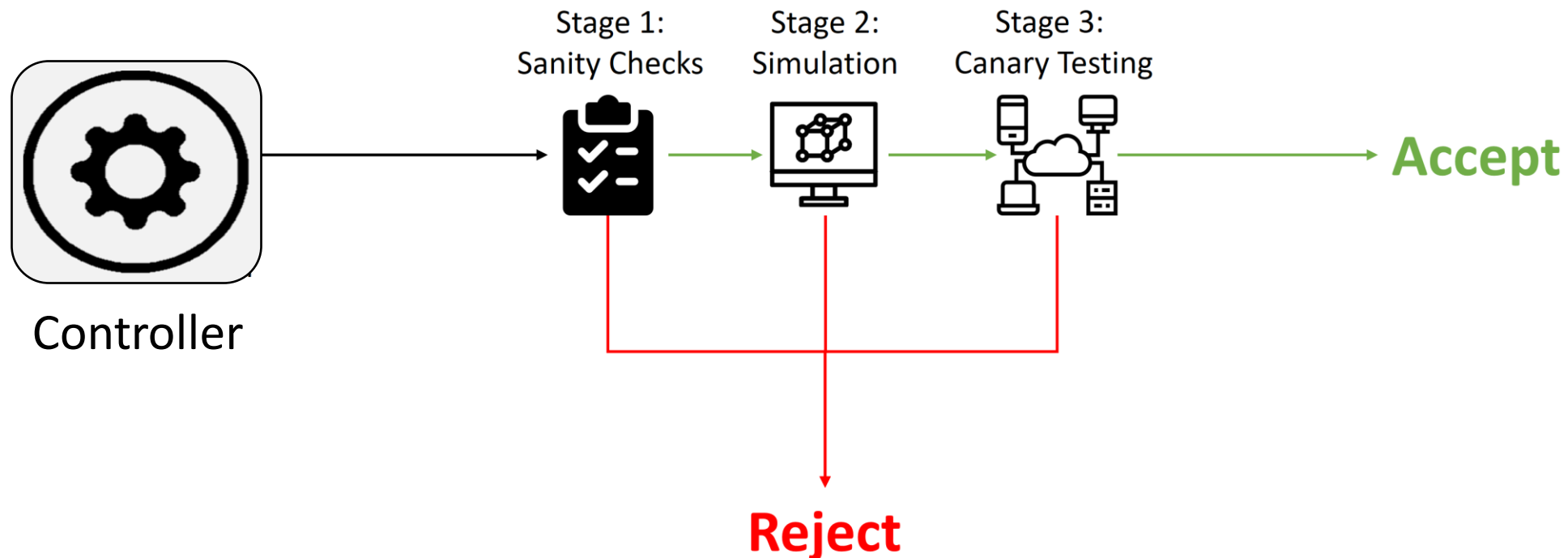
- **3.2.7 Evolution controller**: A controller responsible for the evolution of controllers by manipulating the module instance used within a controller, the structure or topology of connections between modules in a controller and/or the values chosen for the module(s) parameters
- Examples of processes to drive the modification of a controller are:
 - biologically inspired artificial evolution (e.g. evolutionary computing or genetic programming [b-large-evolution, b-evolution])
 - Bayesian optimisation [b-bayesian-radio]
 - game theoretic approaches [b-game-theory].

Examples of Controller Evolution

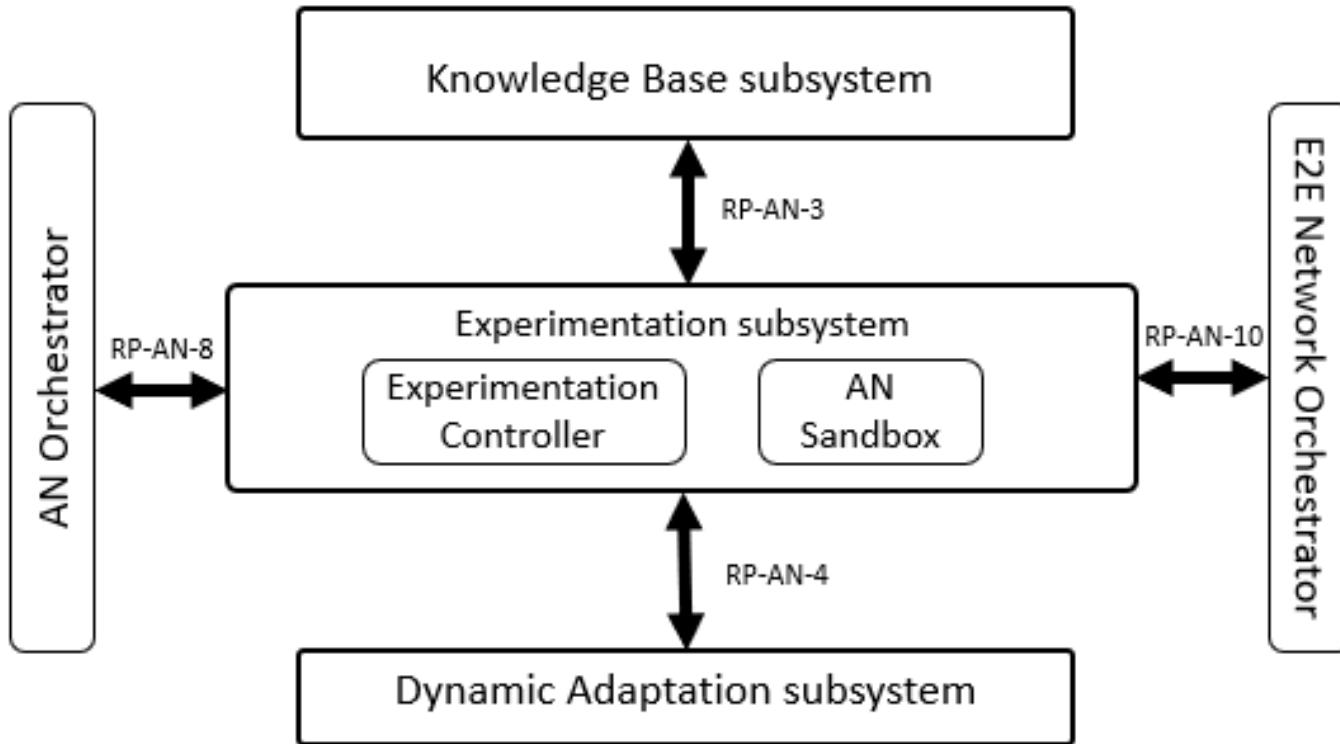
- 1) A “RAN channel scheduling controller” is an example of a controller used to allocate radio resources to users in a multi-user environment. Exploratory evolution is applied to a RAN channel scheduling controller in response to the change of radio channel feedback from the UE. This may include selecting the most appropriate algorithm from a set of alternatives.
- 2) An “anomaly detection controller” is an example of a controller used to detect abnormal states in the operation of a network service, such as security attacks or peaks in resource usage for network function. In this context, the new approaches of data fusion algorithms [b-data-fusion] may be applied. Exploratory evolution is applied to “anomaly detection controller” by optionally using and configuring newly provided data fusion algorithms as the input of an “anomaly detection controller”,
- 3) A “time-to-live controller” is an example of a controller used to configure the time duration for which a certain content is cached in a CDN server. In a time-to-live controller in a caching system at the edge, optimisation of the timeout parameter(s) is an example of application of exploratory evolution.
- 4) A “scaling controller” is an example of a controller used to increase or decrease the resource allocation for a network function. In this context, exploratory evolution may be applied by controlling the configuration of the scaling method of deployed controllers in a specific network domain.

Realtime Online Experimentation

3.2.8 Experimentation: The process of executing the generated potential scenarios and trials upon the controllers, within the parameters of the scenarios and trials and then collecting the results.



Realtime Online Experimentation



3.2.9 experimentation controller: A controller which generates potential scenarios of experimentations based on controller specifications and additional information as provided by the knowledge base, executes the scenarios in the AN Sandbox, collates and validates the results of the experimentation.

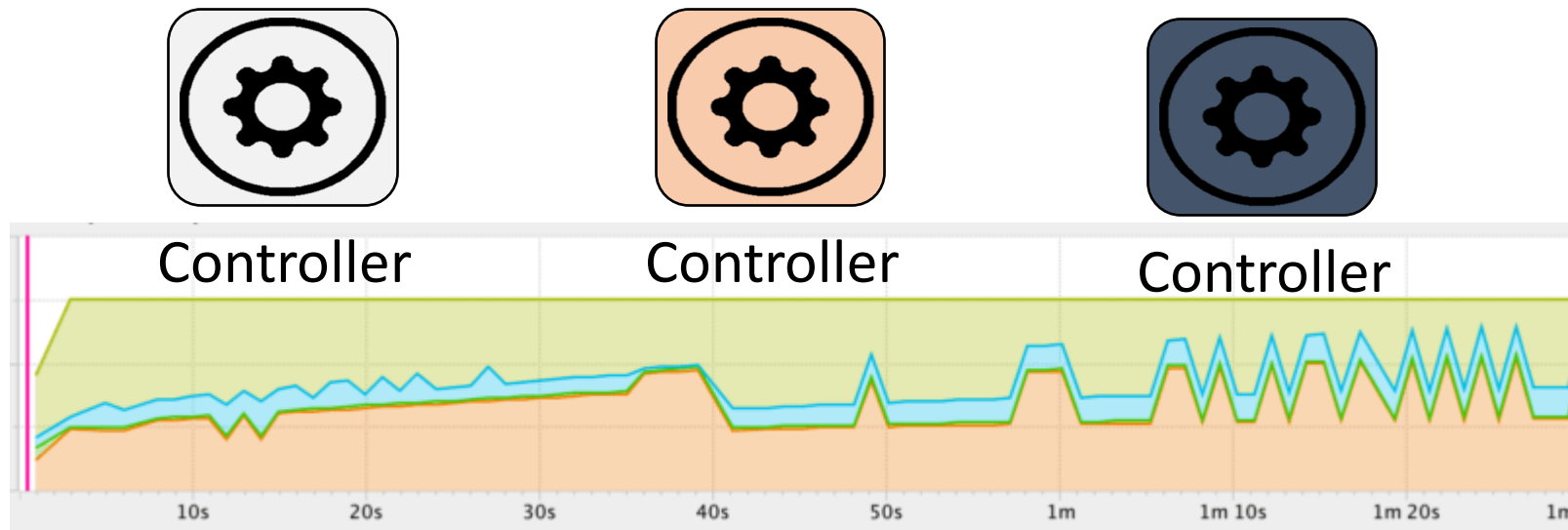
Examples of Controller Experimentation

Examples of experimentation in various application contexts are given below:

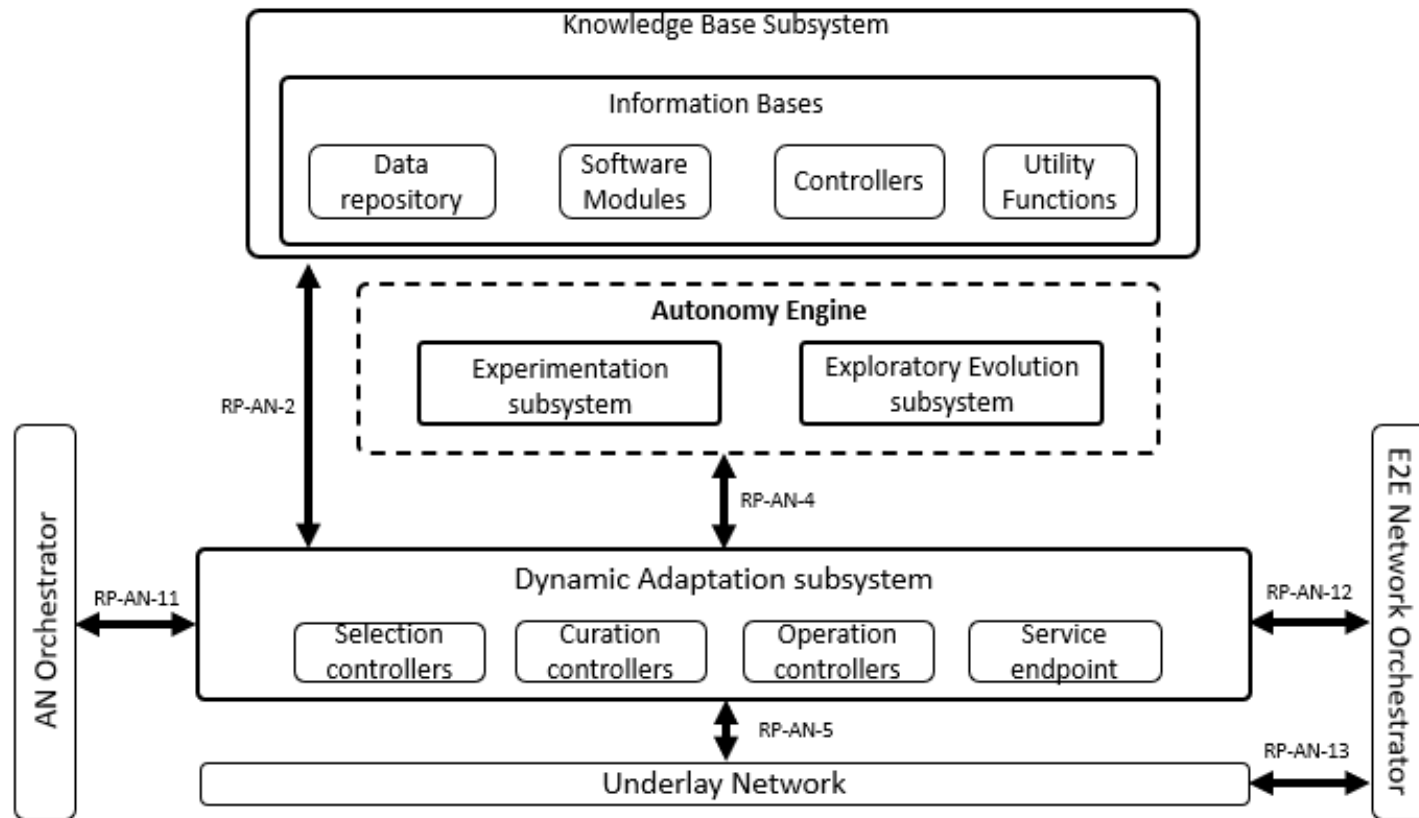
- The use of static “sanity checking” such as formal methods [ITU-T Y.3320] or model checking to ensure that provided management and orchestration solutions are well-formed against pre-defined rules
- The use of simulators or digital twins in offline validation of controllers. These simulators or digital twins can support the same interfaces as underlays.
- The use of digital twins [b-Digital-twin] in online validation of controllers before deployment
 - NOTE 5 - online validation involves use of timescales comparable to real underlays e.g. validation of controllers (xApps) [b-ORAN] using digital twins.
- Combinations of the above to achieve broader coverage of validation, from the offline validation to online validations during the operation of the underlay.

Dynamic Adaptation

- Dynamic adaptation is the **process of continuous integration of controllers to an underlay**, as the underlay undergoes changes at run-time. Integration of controllers may involve multiple domains of the underlay.



Dynamic Adaptation



3.2.1 adaptation controller: A controller responsible for selecting candidate controllers ready for integration and for executing their integration in the underlay network.

Adaptation controller has two parts:

- **Curation controller** (responsible for selection and maintenance of the controllers within the curated controller lists from the evolvable controllers) and
- **Selection Controller** (responsible for the selection of a services' operational controller from the curated controller lists).

Examples of Dynamic Adaptation

Examples of adaptation in various application contexts are given below:

- The need to use different traffic shaping algorithms for various geographical contexts, such as urban vs rural
- Business priorities may change over a period of time, e.g. prioritization of performance KPIs over energy efficiency or prioritisation of internal applications over third party applications. These changes in business priorities may necessitate the use of different virtual machine or container scheduling controllers.
- There could be a need to deploy new technology in order to improve or optimise operation, including adding new capabilities that previously did not exist. E.g. new AI/ML algorithms or new data fusion approaches to blend the increasing number of data sources.
- There could be a need to deploy new technology in order to address errors or faults. E.g. data acquisition or actuation software for new hardware devices or adaptation software to account for incompatibilities in deployed technology.

Architecture Components

Evolution Controller

Creates and modifies a controller in accordance with the system under control and the real-time changes therein.

Knowledge Base

Manages knowledge derived from and used in autonomous networks. It is updated and accessed by various components in the autonomous network.

AN Orchestrator

managing workflows and processes in the AN and steps in the lifecycle of controllers

Experimentation Controller

Validates controllers using inputs from a combination of underlay network, simulators and/or testbeds.

An Sandbox

environment in which controllers can be deployed, experimentally validated with the help of (domain specific) models of underlays

Adaptation Controller

Continuous integration of controllers to an underlay, as the underlay undergoes changes at run-time.

Architecture Components

FGAN-I-345-R2

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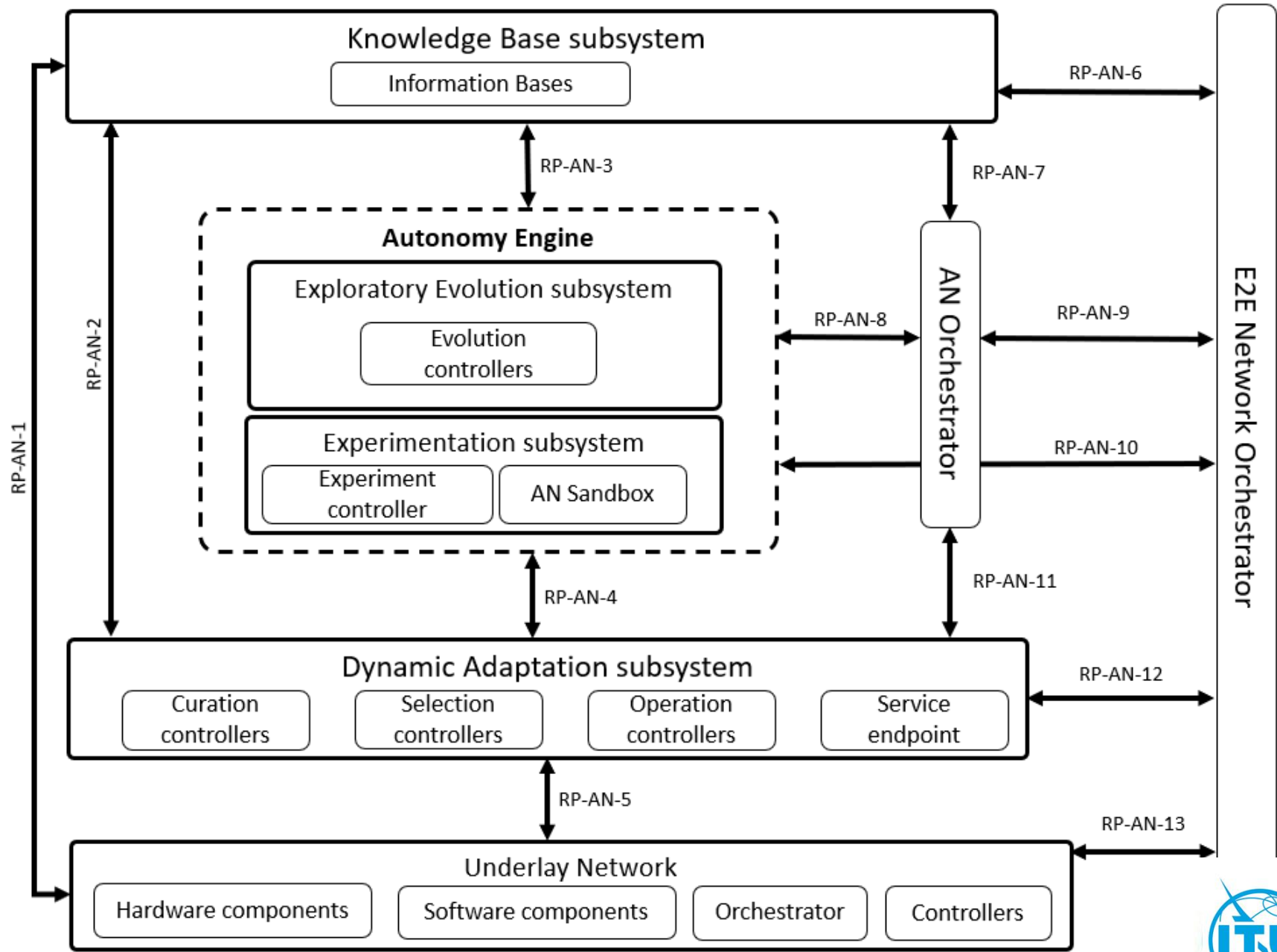
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AN Orchestrator

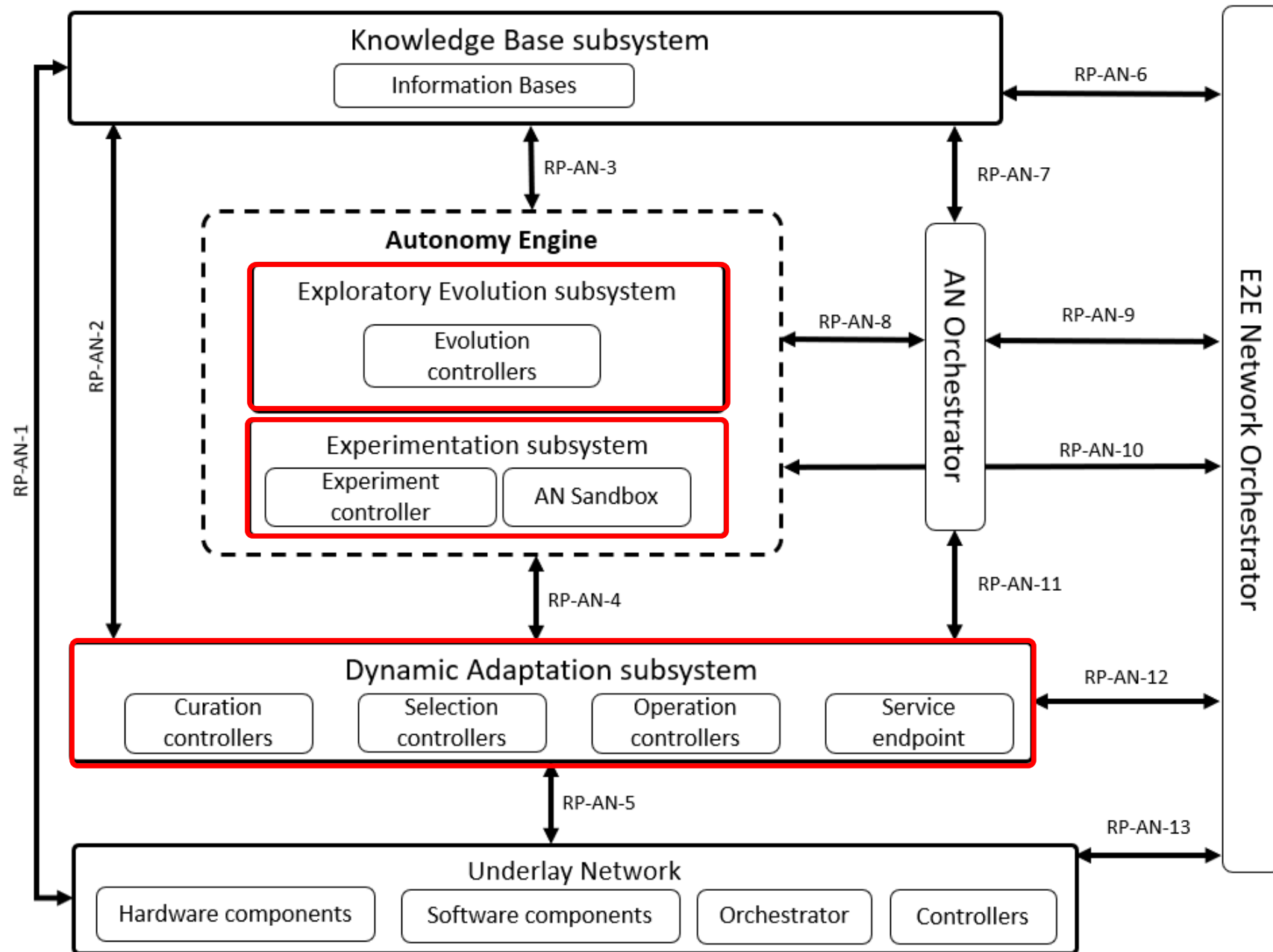
managing workflows and processes in the AN and steps in the lifecycle of controllers

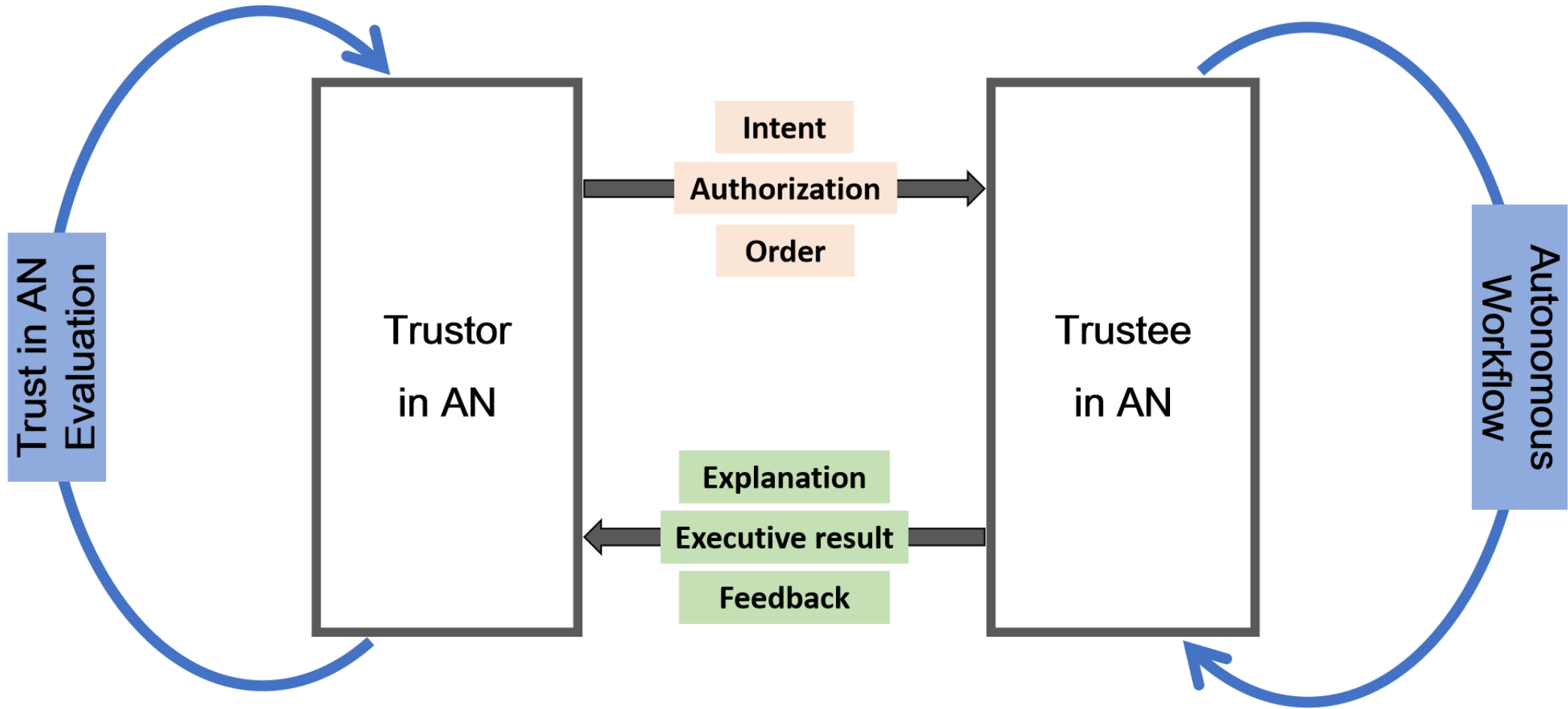
Adaptation Controller

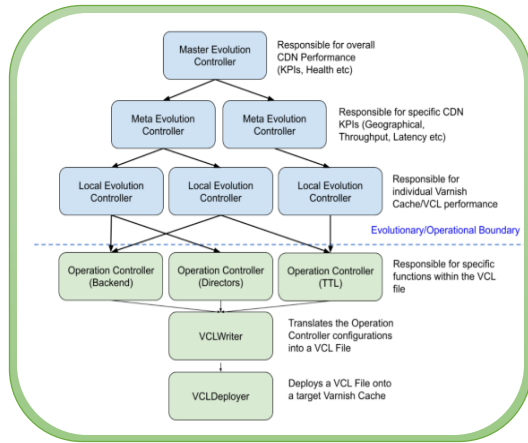
Continuous integration of controllers to an underlay, as the underlay undergoes changes at run-time.



3 Key Concepts

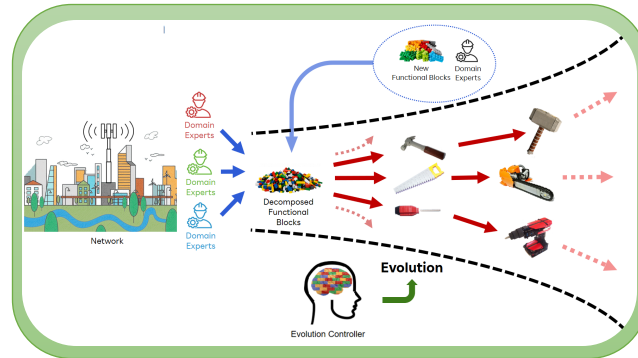




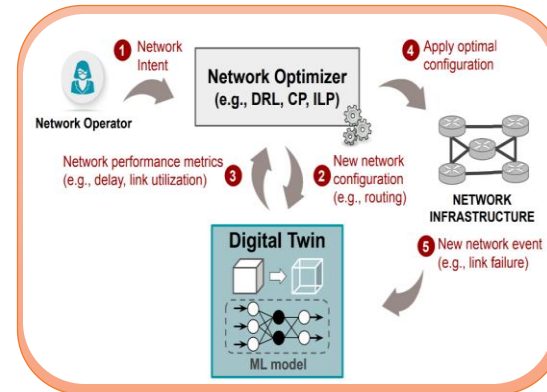


Towards evolution-based autonomy in large-scale systems.

Evolutionary Autonomous Networks



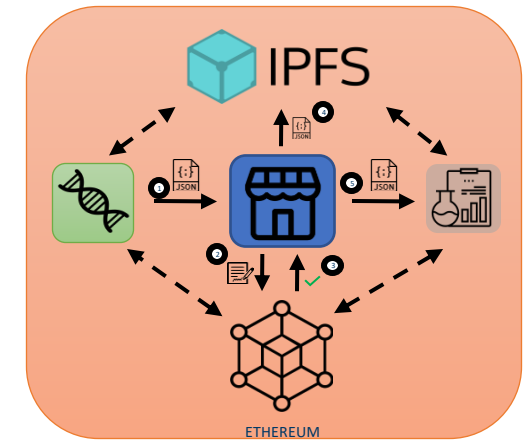
Create



Network Digital Twin: Context, Enabling Technologies and Opportunities

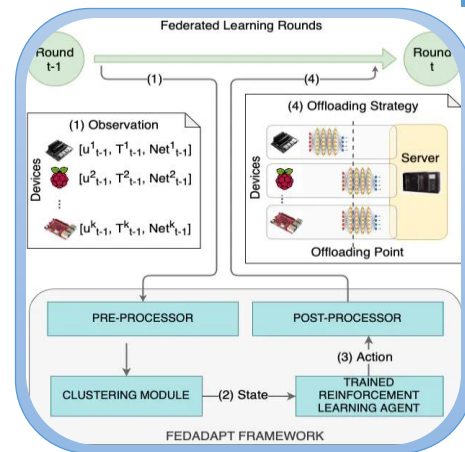
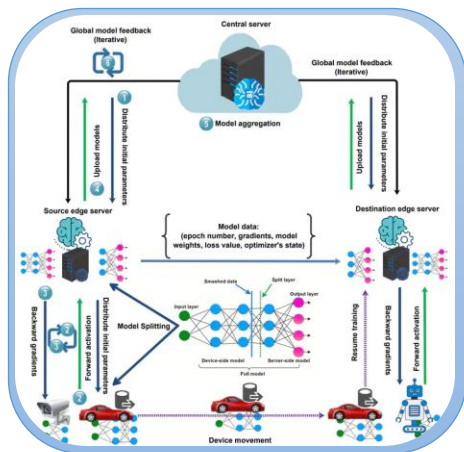
Validate

Blockchain Marketplace For Autonomous Networks



Apply

FedFly: Towards Migration in Edge-based Distributed Federated Learning



FedAdapt: Adaptive Offloading for IoT Devices in Federated Learning

Herding the FLOQ: Flow Optimised Queuing

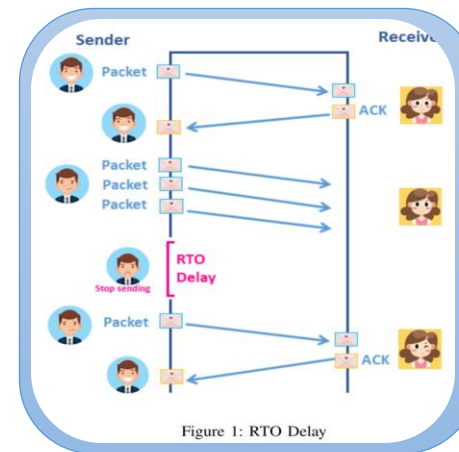
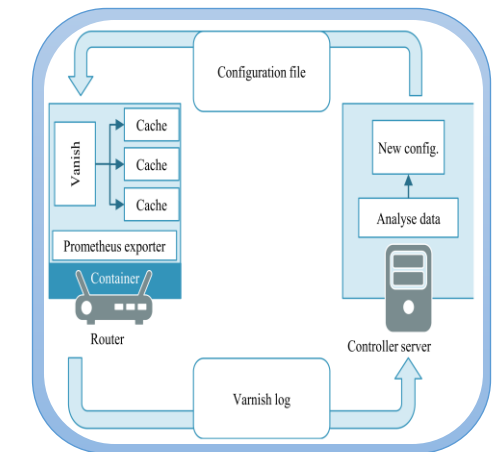


Figure 1: RTO Delay



A Feasibility Study of Cache in Smart Edge Router for Web-Access Accelerator

Create Logic

- Evolutionary Computing
- Fitness Function Decomposition
- Ontology Guided Creation
- Meta-evolution
- Automated Code Synthesis

Validate Logic

- Digital Twin
- Formal Verification
- Co-simulation
- Experimental Design
- Chaos Testing

Apply Logic

- Resource Allocation Problems
- Parallelisation
- Virtualisation
- Information Centric Networking
- Telco Cloud / O-RAN

Aid Logic

- Ontology & Taxonomy Generation
- Levels of Autonomy
- Intent-Based Systems/Networks
- Explainable Operation



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